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Despliegue pasivo amortiguado de estructuras de materiales compuestos



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Palabras clave: Resinas epoxy Propiedades amortiguamiento Estructuras desplegables Comportamiento dinámico Se ha identificado un nuevo material, no usado en aplicaciones espaciales, que tiene propiedades muy interesantes: una resina epoxy de menor rigidez y mayor amortiguación de las que se utilizan en la industria espacial, que se puede mezclar con las que actualmente se utilizan. La mezcla de éstas puede ser utilizada en componentes CFRP cuyas propiedades de rigidez y amortiguación se podrían ajustar según se necesite.

Una aplicación posible para este nuevo material son los mástiles desplegables de CFRP, con rótulas *tape-spring*. Este tipo de rótulas han mostrado ser muy útiles, pero tienen un comportamiento dinámico muy brusco que puede dañar los componentes desplegables o la estructura que los contiene. El uso de resinas epoxy flexibles en las rótulas de CFRP puede introducir unos efectos amortiguadores que mejoren este comportamiento dinámico.

El objetivo de este proyecto es verificar la aplicabilidad de esta mezcla de resinas epoxy rígidas y flexibles para mejorar el comportamiento dinámico de las rótulas *tape-spring*. Los resultados obtenidos son muy prometedores. Muestran que es posible customizar las propiedades de algunos componentes mediante una mezcla adecuada de resinas. No obstante, estudios adicionales son necesarios para asegurar el correcto comportamiento en condiciones espaciales. La validación de este material puede abrir nuevas puertas en aplicaciones espaciales en las que sea crucial una correcta combinación de rigidez-amortiguamiento.

Passive damped deployment of full composite structures



Keywords: Epoxy resins Damping properties Deployment structures Dynamic performance A new material, currently used in non-spatial applications, with interesting properties has been identified: a flexible epoxy resin with lower stiffness and higher damping than the space used resins and that is miscible with these ones. Such a mixed material could be used in CFRP components which properties (stiffness and damping) could be customised.

One possible application has been selected for this study: the deployment of full CFRP structures composed of thin-walled composite deployable booms with tape-spring hinges on them. These kind of passive springs have been shown to be very powerful, but they have also shown a hard dynamic behaviour that can produce damages to the deployed items or their hosting structure. The partial use of flexible epoxy resins in the CFRP hinges can introduce an efficient damping in the deployment and relief of this dynamic effect.

The objective of this activity is to verify the feasibility of the use of a mixture of rigid and flexible epoxy resins for obtaining better dynamic performances of CFRP tape springs. The results of this study are very promising. They show that it is possible to customise the properties of some components by finding the adequate mixture of resins. However, additional studies are necessary to assess good performances in space environment. The validation of this material can open the door to new space applications where the proper combination of stiffness and damping is crucial.



1 Scope of the study

This study aims to verify if a mixture of rigid and flexible epoxy resins, reinforced with carbon fibres, could change its mechanical properties (stiffness and damping) by changing the resins proportion. If so, this fact could be used to improve the performances of some space applications.

Once these materials were characterised experimentally, the stiffness and damping properties obtained from the tests were used in finite element simulations to study the effect of the different matrix mixes in a potential space application: the deployment of a tubular tape-spring composite hinge.

2 Materials and methods

Four resins mixtures of rigid and flexible epoxy resins were considered in this project:

Table 1: Resin system combinations.

| Material Reference | Material label | Rigid resin (%) | Flexible resin (%) |
|-----------------------|-------------------|--------------------|-----------------------|
| 1 | R25 | 25 | 75 |
| 2 | R50 | 50 | 50 |
| 3 | R75 | 75 | 25 |
| 4 | R100 | 100 | 0 |

These resins mixtures were reinforced using different layers of carbon fibre plain fabric to manufacture the test coupons, depending on the type of test performed on the coupon.A series of tests were conducted in order to determine the materials properties:

- Stiffness was characterised through the Young's modulus in both axial tensile tests and four-point bending tests:
 - Axial tensile tests are designed to measure the tensile modulus of elasticity. A universal test machine has been used.
 - The objective of the four-point bending tests is to measure the bending modulus of elasticity. A universal test machine with adequate test fixtures has been used.
- For measuring the damping, the amplitude decay logarithm increment method was used and the critical damping ratio and an equivalent Rayleigh stiffness-proportional damping model coefficient [1] were obtained.
- The pre-load loss was also investigated through creep tests in which the capability of the material for bearing a constant load for a long time is verified. In these tests, the coupons are bent 180 degrees with a radius of 20 mm. The applied load was maintained constant and the position of the tip of the coupon was registered over time.
- The thermal stability at high temperatures was verified by applying the following cycle: 20 °C to 150 °C, heat up rate 1 °C/min, and dwell 60 minutes at 150 °C.

Once these materials were characterised, they were used in finite element simulations to study the deployment of a tubular tape-spring composite hinge. MSC/Marc finite element software was used for the analyses.

The four considered materials had the same laminate layout (2 layers ± 45 , with a total thickness of 0.22 mm). The following image shows the overall geometry of the model and the fibre orientation (± 45) with respect to the hinge longitudinal axis.



Figure 2.1 : Fibre orientation.

Each material was modelled as an equivalent homogeneous orthotropic shell. From the symmetry of the layout, the longitudinal and transversal Young's moduli are equal and determined from the tests. The shear modulus was approximated to be twice the longitudinal modulus. This ratio was obtained in previous studies of a similar material [2]. The Poisson ratio was considered to be 0.76 for all materials [2]. Its influence in the results is negligible. This way, the only parameter related to stiffness to be determined by test is the longitudinal Young's modulus.

On the other hand, damping is perhaps the most unrealistic part of any dynamic model. The mechanisms by which a structure dissipates mechanical energy are not well understood and, consequently, damping models are distant approximations. Different damping models can be found in bibliography, all giving different results. Usually, the only feature that can be demanded to a damping model is the overall loss of energy that produces to be correct. The damping model used in the simulations was the Rayleigh's proportional damping model with only stiffness proportional coefficient β [1]. Two approaches were considered:

- a) <u>' β approach'</u>: Assuming that the parameter β found in damping tests is a material property and, thus, has the same value in all conditions (for any geometry made with the tested material).
- b) <u>' ξ approach</u>': Assuming that the critical damping ratio ξ found in damping tests is a material property and consequently it has the same value in all conditions (for any geometry made with the tested material). For this assumption, and due to the fact that only the Rayleigh's parameters can be introduced in MSC/Marc software, the following equivalence is established: $\beta = \frac{\xi}{\pi f_n}$ being f_n the natural frequency of the tubular tape-spring hinge model. This approach was only carried out for the materials labelled as R100 and R25.

The finite element model took into account the following issues:

- Material linear behaviour.
- Damping is modelled with Rayleigh's model, considering only the stiffness term.
- Large displacements.
- Implicit numeric solver.

The four hinges had the same geometry which is shown below:



Figure 2-2: Hinge geometry

Following figure shows the boundary conditions applied to the FEM for its initial folding manoeuvre:



Figure 2-3: Boundary conditions.

3 Results

3.1 Materials Tests Results

3.1.1 Axial Tensile Test

The tensile tests were carried out until fracture. The following table shows the measured average Young's modulus at the linear part of the stress-strain curve, and the ultimate strength:

| Table 2: Average | Young | 's modulus | and material | strenath |
|------------------|--------|------------------|--------------|----------|
| | 100119 | 0 1110 0 0 0 0 0 | anamatona | ounguin |

| Material (rigid resin percentage) | Young's modulus (GPa) | Strength (MPa) |
|--------------------------------------|-----------------------|-------------------|
| 100 | 6.02 | 172 |
| 75 | 1.38 | 151 |
| 50 | 0.55 | 112 |
| 25 | 0.27 | 53 |

3.1.2 Four Point Bendings Test

The following table shows the average calculated modulus of elasticity.

Table 3: Average bending stiffness coefficient and calculatedYoung's modulus.

| Material (rigid resin percentage) | Average stiffness (N·mm ⁻¹) | Young's modulus (GPa) |
|--------------------------------------|--|-----------------------|
| 100 | 17.10 | 6.75 |
| 75 | 15.29 | 6.04 |
| 50 | 10.74 | 4.24 |
| 25 | 5.04 | 1.99 |

3.1.3 Damping test

Next table shows the obtained average damping ratio ξ , natural frequency f_n and corresponding Rayleigh's model β coefficient for each material.

Table 4: Average damping ratio, natural frequency and Rayleigh's model β coefficient.

| Material (rigid resin percentage) | Damping ratio ξ | Natural frequency (Hz) f_n | Rayleigh's coefficient (s·rad ⁻¹) $\beta = \frac{\xi}{\pi f_n}$ |
|---|---------------------|------------------------------|--|
| 100 | 0.010 | 262.84 | 1.20E-05 |
| 75 | 0.014 | 241.93 | 1.84E-05 |
| 50 | 0.023 | 229.65 | 3.17E-05 |
| 25 | 0.038 | 224.61 | 5.38E-05 |

3.1.4 Creeps Test

The coupons with 100% and 50% rigid resin respectively collapsed after only one day. It was found out that the designed test rig did not maintain a constant load over the coupon, contrary to what could be thought. As the material

creeps and its stiffness is reduced, the change in the coupon shape increases the moment at the critical point, which in turn increases the deformation, and so on, which can cause the collapse of the coupon. Creep test methodology must be reviewed for avoiding the increasing of the coupon stress.

Two coupons (75% and 25% rigid resin respectively) survived the objective time of 30 days. Next figure shows the evolution of the coupon tip height along the time.



Figure 3-1: Creep tests results

3.1.5 Termal Stability Tests

No effect on the samples was visually detected neither during the heat up ramp nor the 150 °C dwell. After the 60 min at 150 °C all of them presented a similar behaviour to the sample at room temperature. After the test, visual inspection showed no failures, defects or micro-cracking in the coupons.

3.2 Potential Space Application

The material properties obtained in the material characterisation tests were used to simulate the tubular tapespring composite hinge.

The folding simulation was carried out in two stages. A tapespring hinge has a high bending stiffness in the fully deployed configuration. Therefore, to reproduce the folding a hinge without imposing very large strains, the process begins by pinching and flattening the hinge between two rigid surfaces. Then, the folding itself is produced.

Once the hinge is completely folded, the system is stable after a short period of time. The deployment simulation starts when one of the pivot points is released.



Figure 3-2: Analysis sequence



Figure 3-3 (cont'd): Analysis sequence

3.3 β Approach

Table 5 shows a summary of the simulations results for the β approach.

| Table 5: Results summary (| $(\beta \text{ approach})$ |
|----------------------------|----------------------------|
|----------------------------|----------------------------|

| Hinge | Max. Angular velocity | Max. Reaction torque at the embedment | Reaction torque at the embedment at 180° | Min. Reaction torque at the embedment (before 150°) | Max. Von Mises stress | Deployment time |
|-------|-----------------------------|---|---|--|--------------------------|--------------------|
| | (rad/s) | (Nm) | (Nm) | (Nm) | (MPa) | (s) |
| R100 | 28.3 | 11.6 | 1.00 | 0.082 | 718 | 0.259 |
| R75 | 33.9 | 10.4 | 0.90 | 0.072 | 644 | 0.274 |
| R50 | 21.7 | 8.2 | 0.64 | 0.054 | 464 | 0.321 |
| R25 | 17.8 | 3.5 | 0.31 | 0.0247 | 220 | 0.465 |

Table 5 (cont'd): Results summary (β approach)

| Hinge | Bending Modulus | Max. strain energy | Kinetic energy at 0° | Dissipated energy at 0° | Energy ratio at 0° (Dissipated energy / Max. strain energy) |
|-------|--------------------|-----------------------|-------------------------|----------------------------|---|
| | (GPa) | (J) | (J) | (J) | - |
| R100 | 6.75 | 0.670 | 0.584 | 0.068 | 0.102 |
| R75 | 6.04 | 0.602 | 0.537 | 0.055 | 0.091 |
| R50 | 4.24 | 0.433 | 0.377 | 0.047 | 0.11 |
| R25 | 1.99 | 0.205 | 0.183 | 0.019 | 0.093 |

The energy ratio shown in

Table **5** compares the dissipated energy with the initial strain energy before deployment (last column data). This value is approximately constant in the four simulations with the different material models and does not follow any understandable rule. This is a contradiction with what is found in the damping tests (the higher the flexible epoxy resin percentage, the higher the ratio of dissipated energy with respect to the total energy). It has been thought that the origin of this contradictory result is the assumed hypothesis that the Rayleigh's damping model parameter is a material constant that can characterise the damping behaviour of the material in all conditions. So, this hypothesis should be verified.

3.4 ξ Approach

The same folding and deployment manoeuvres were simulated with the R100 and R25 materials but following the ξ approach. Following table shows the results obtained in terms of relevant deployment features for the considered models.

Table 6: Results summary for the hinges (ξ approach).

| Hinge | Max. Angular velocity (rad/s) | Max. Reaction torque at the embedment (Nm) | Reaction torque at the embedment at 180° (Nm) | Min. Reaction torque at the embedment (before 150°) (Nm) | Deployment time (s) |
|-------|-------------------------------------|--|---|--|---------------------------|
| R100 | 28.3 | 11.1 | 1.07 | 0.067 | 0.263 |
| R25 | 12.6 | 3.36 | 0.32 | 0.026 | 0.475 |

| Hinge | Bending Modulus | Max. strain energy | Kinetic energy at 0° | Dissipated energy at 0° | Energy ratio at 0° (Dissipated energy / Max. strain energy) |
|-------|-----------------|--------------------|----------------------|-------------------------|---|
| | (GPa) | (J) | (J) | (J) | - |
| R100 | 6.75 | 0.67 | 0.567 | 0.0831 | 0.124 |
| P 25 | 1 00 | 0.205 | 0 173 | 0.031 | 0 151 |

Table 6 (cont'd): Results summary (ξ approach).

These results show a substantial increase of the energy ratio shown in the last column when the percentage of flexible resin increases, which is reasonable and shows very promising results for this space application.

4 Weight and Cost Study

A coarse comparison between the weight, performance and manufacturing and assembly costs of a full CFRP deployable boom with integrated slotted hinges with different epoxy resins and the same structure with traditional metallic hinges was done for a typical space application. Possible future Thor ESA mission was selected, which contains several booms. Two of them are part of the magnetometer and their design was studied. The magnetometer contains two 6.3 meter long boom deployed from three segments. Following figure shows a spacecraft image and the stowed booms on the spacecraft.



Figure 4. 1: Thor mission booms and magnetometer stowed configuration.

The following conclusions were obtained:

- The use of CFRP slotted hinges made with 100% rigid epoxy resin can reduce the weight of the boom (9% for the considered boom) and its cost (to 64%) compared to the solution with metallic hinges for the same mechanical requirements.
- The use of CFRP slotted hinges made with 25% rigid epoxy and 75% flexible epoxy can maintain the weight of the boom, reduce its cost (to 64%) compared to the solution with metallic hinges and additionally increase its damping properties to values where the dynamic effects of the environmental loads, deployment manoeuvre and deployed loads can be mitigated.
- Additional weight can be saved at the expense of a reduction in damping (but still being more damped that a metallic hinge solution), as it is shown in the following figure:



Figure 4. 2: Mass/damping comparison for booms with similar behaviour and other possible intermediate solutions (in dashed line)-

Additionally, a potential pointing accuracy improvement of the application has been outlined, due to its simpler design compared to the boom with metallic hinges.

5 Conclusions

The results of this project have proven that the concept of a material which properties (stiffness and damping) can be tuned for the intended application is feasible: a carbon fibre reinforced mixture of rigid and flexible epoxy resins changes its stiffness and its damping capacity as the proportions of the resins in the mixture changes.

Both properties are strongly related (one increases when the other decreases), but it is likely possible to find compromise points between them that improve a specific space application. In particular, it is thought that a CFRP slotted hinge can be developed with this material and its stiffness and damping properties can be adapted to a specific mechanical requirement.

Additionally, it has been shown that a space application such the one presented in the present study would be improved in terms of weight and cost if CFRP slotted hinges were used.

Next intended steps for this activity are to further investigate on the material behaviour and its damping modelling, and to develop, manufacture and test a breadboard of a space application where its advantages can be demonstrated.

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